BSC IN ELECTRICAL AND COMPUTER ENGINEERING

L.EEC025 - FUNDAMENTALS OF SIGNAL PROCESSING

Academic year 2023-2024, week 1 PL preliminary problems

Topics: Introduction to Matlab, revisiting the discrete-time convolution, FIR/IIR discrete-time systems

Problem 1

Create an .m file of Matlab commands implementing the following operations:

- asks the user to enter an integer number N (N>30) using the keyboard,
- creates a line vector, n, including the integers 0, 1, ..., N-1,
- creates a line vector $h = \alpha^n$ with $\alpha = 0.95 \exp(j\pi/3)$,
- represents graphically the absolute value of the elements of vector h, using vector n to index the abscissae axis;
- also adds the following commands:

```
>> xlabel('n \rightarrow');
>> ylabel('Magnitude \rightarrow');
>> legend('Envelope')
>> title(Complex Exponential');
```

- (OBS: always use command pause; after a plot or stem command)
- starts a new graphical window using figure (2); this figure will then be split in order to represent three plots vertically (i.e., it will be configured as a 3×1 matrix),
- uses command stem to represent in the upper part of figure 2, the real part of vector h, and using vector n to index the abscissae axis:
- creates a line vector x, comprising N elements and whose non-zero values are given by the discrete-time sequence u[n-20]-u[n-30],
- uses command stem to represent in the middle part of figure 2, vector x, and using vector n to index the abscissae axis;
- uses command conv to create in vector y the result of the discrete convolution between the real part of vector h and vector x;
- displays the message "Convolution completed!",
- shows the result of commands size (y) and length (y) (what is the difference?),
- uses command stem to represent in the lower part of figure 2, the first N elements of vector y using symbol 'pentagram', and using vector n to index the abscissae axis;
- adds suitable labels to the abscissae and ordinates axis of figure 2.

Find yourself the answers to these questions:

- i) Commands sum (h.*conj (h)) and h*h' deliver the same result, why?
- ii) What is the difference between h*h' and h*h.'? And if we had instead h.*h?
- iii) Where we used command conv, could we have used command filter?
- iv) What is the difference between commands who and whos?

Problem 2

A discrete-time system is described by the difference equation $y[n] = \frac{1}{4}(x[n] + x[n-1] + x[n-2])$.

- a) Obtain its impulse response, h[n].
- **b)** Obtain the output of the system to the input $x[n] = 0.5\delta[n] + \delta[n-1] + 0.5\delta[n-2]$.
- c) Confirm the previous result using Matlab.

Problem 3

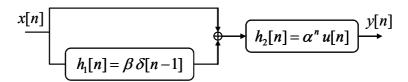
The impulse response of a discrete-time system is given by $h[n] = 2^{-n}u[n]$. Obtain the output of the system when the input is x[n] = u[n] - u[n-10]. Confirm the result using Matlab.

Problem 4

Obtain the impulse response of the system that is described by the difference equation y[n] = 0.3x[n] + 0.7y[n-1] and assuming that it starts from rest. Confirm the result using Matlab.

Problem 5

In the illustrated discrete-time system (consisting of several subsystems) α and β are real-valued constants whose absolute value is less than the unity.



- a) Obtain the impulse response of the complete system, h[n].
- **b)** Obtain the frequency response of the complete system, $H(e^{j\omega})$.
- c) Obtain a difference equation (relating y[n] and x[n]) describing the complete system.