

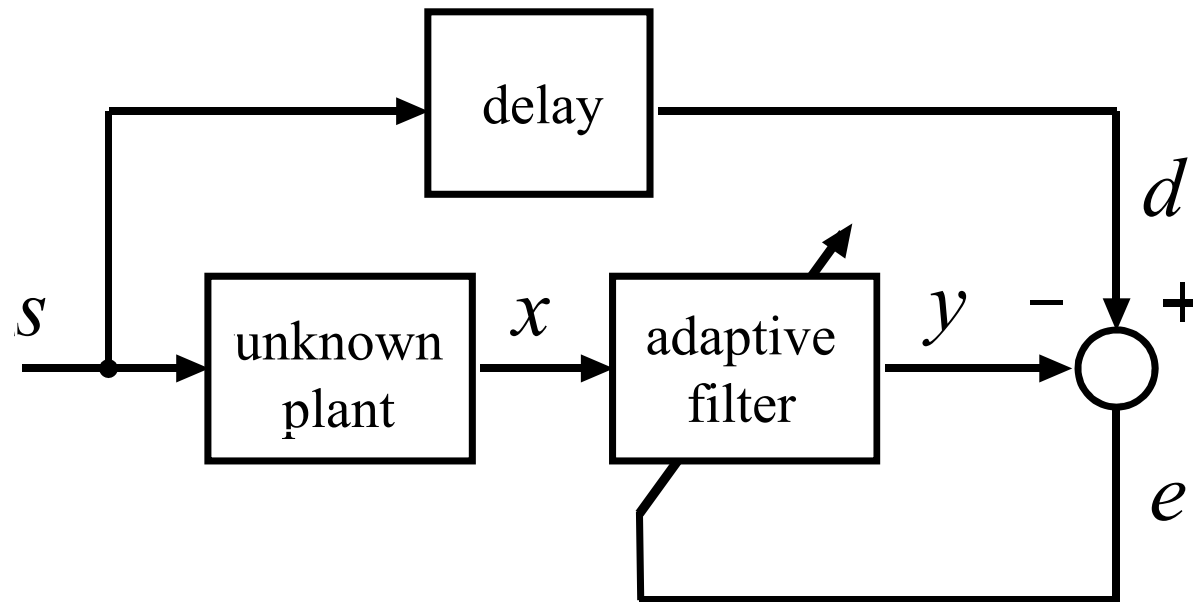
arm

Adaptive Filters

Equalization and Noise Cancellation

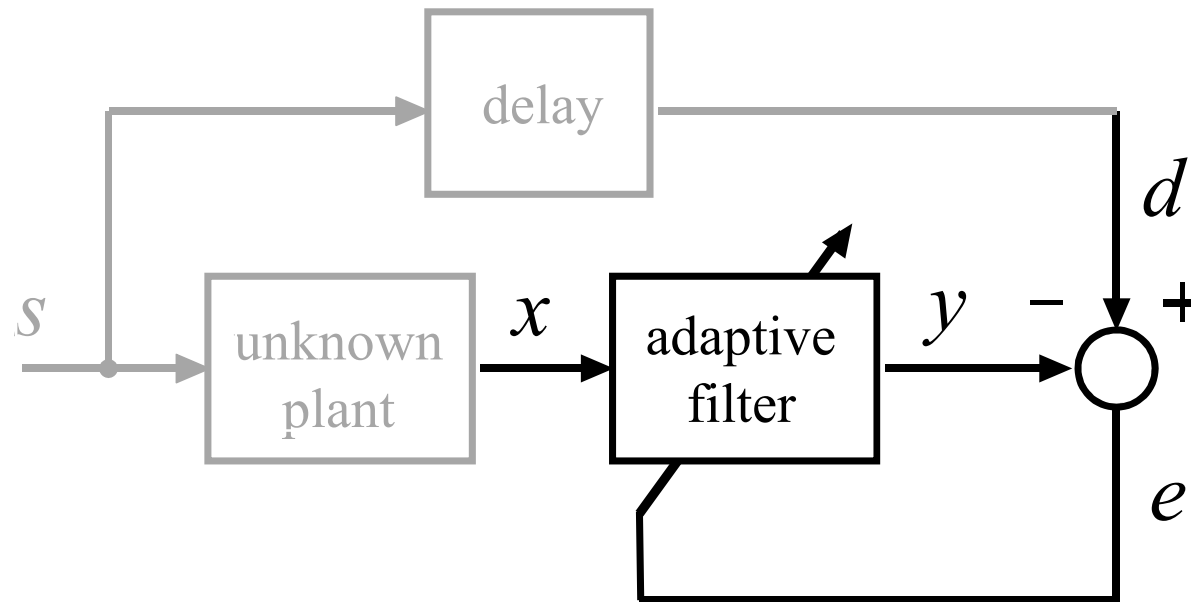
c) Equalization

- Adaptive filter tries to recover delayed version of s from x .



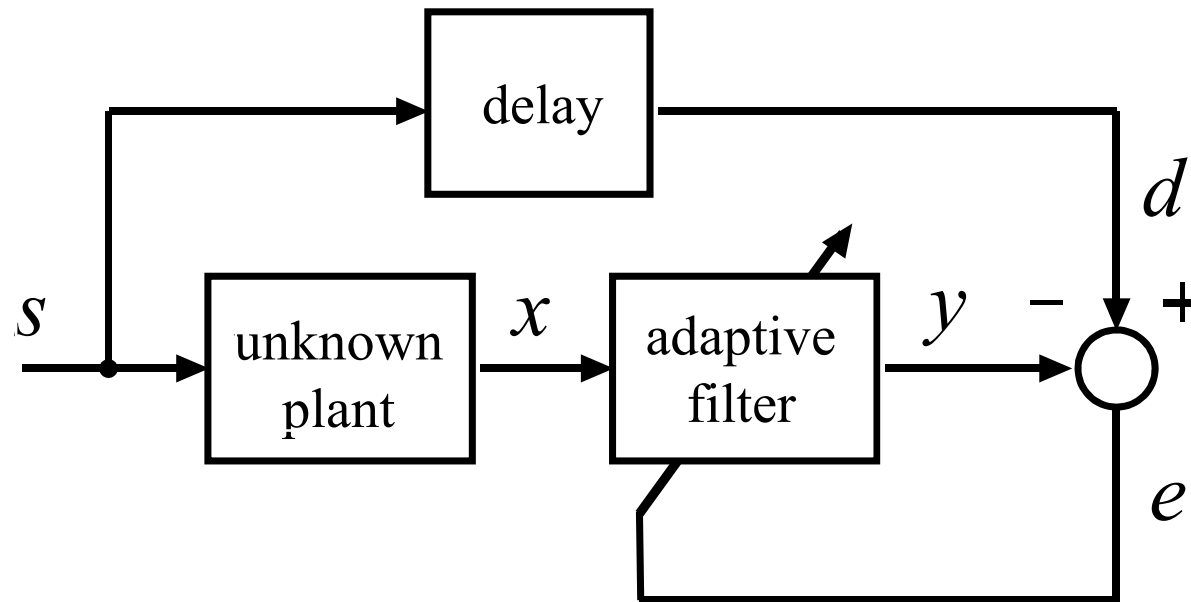
c) Equalization

- Adaptive filter tries to recover delayed version of S from \mathcal{X} .



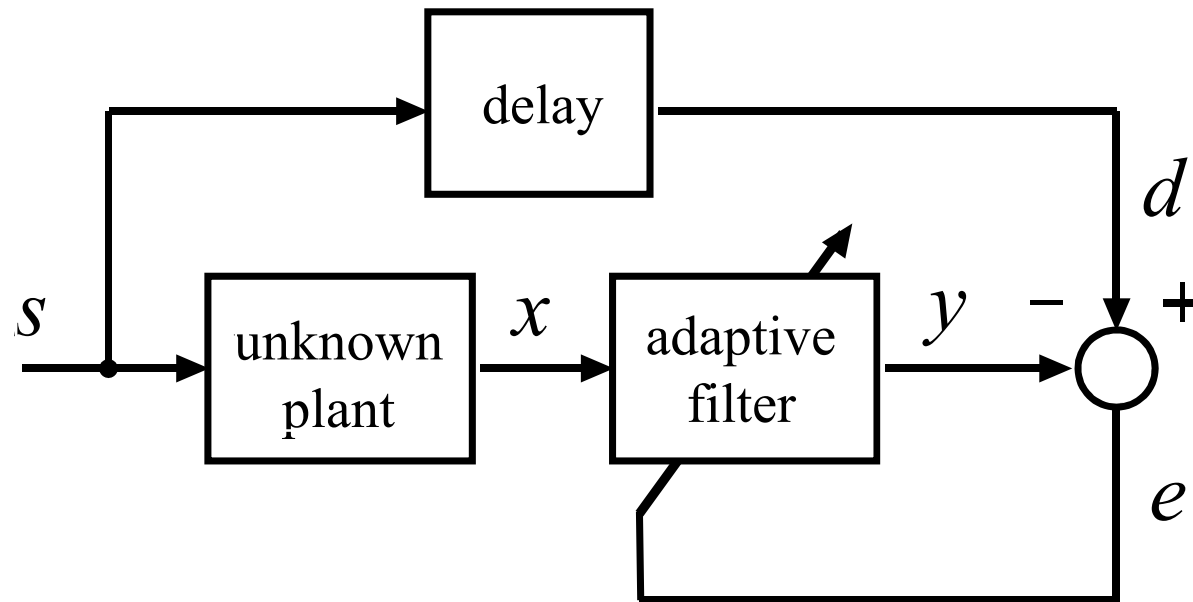
c) Equalization

- x is formed by passing s through unknown plant.



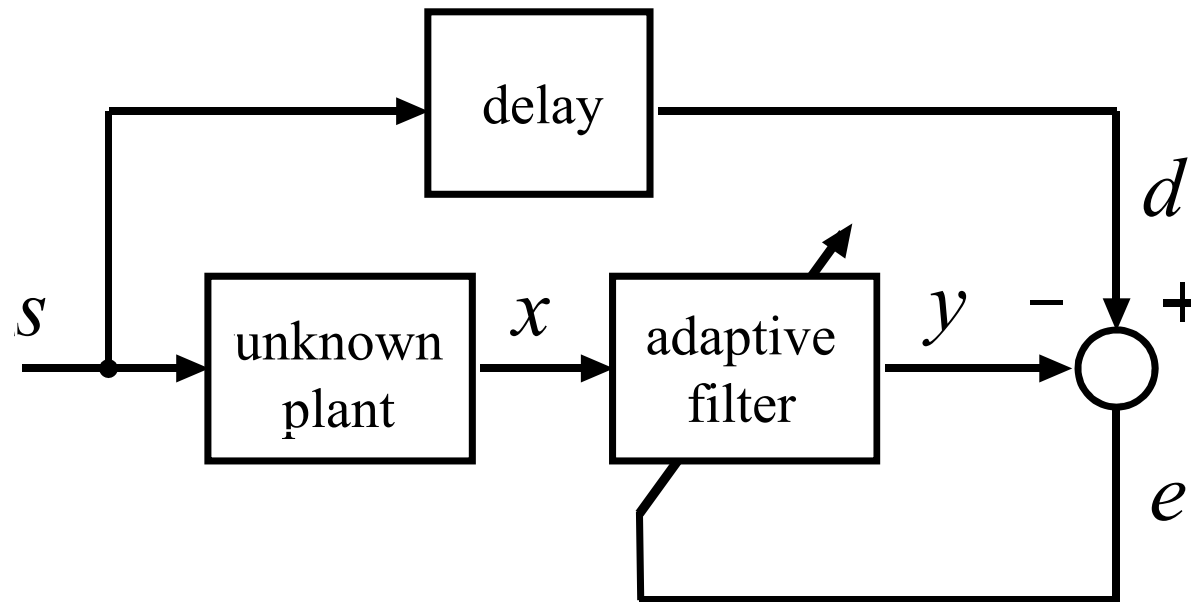
c) Equalization

- Delay is included to allow for propagation of signals through plant and filter.



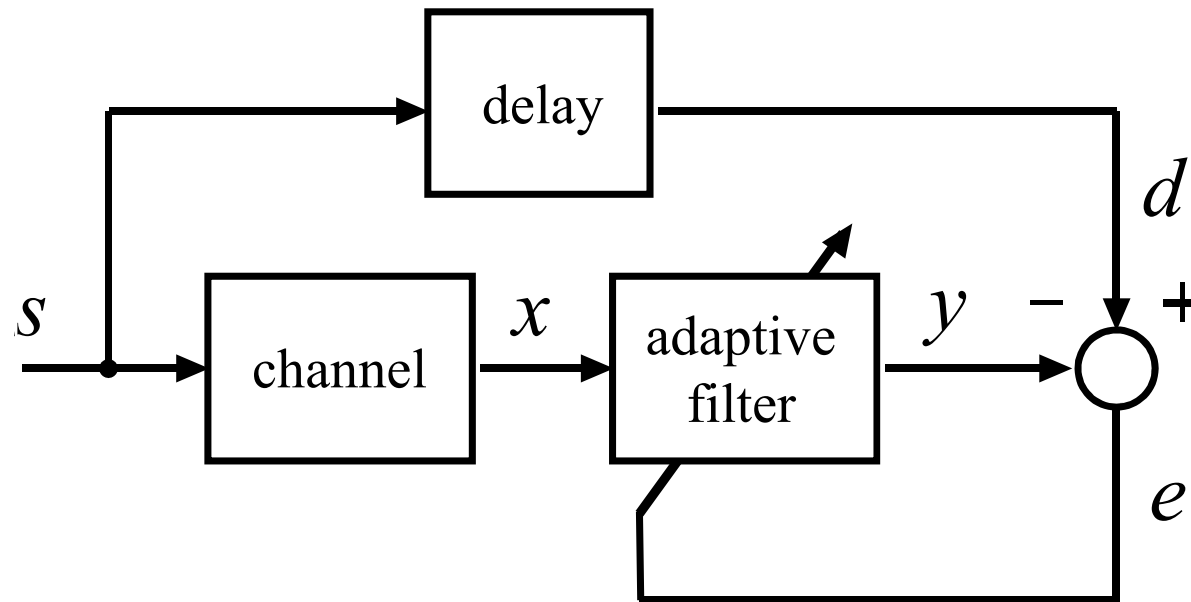
c) Equalization

- After (successful) adaptation, adaptive filter takes on inverse characteristics of plant.



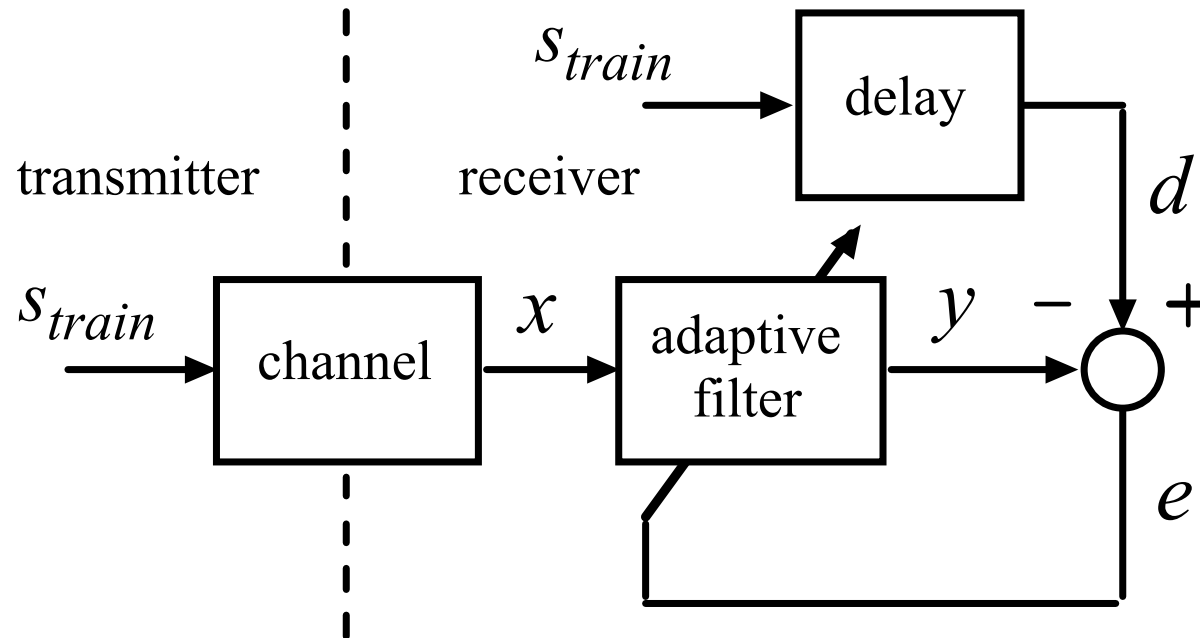
c) Equalization Application

- Unknown plant might be a communication channel.



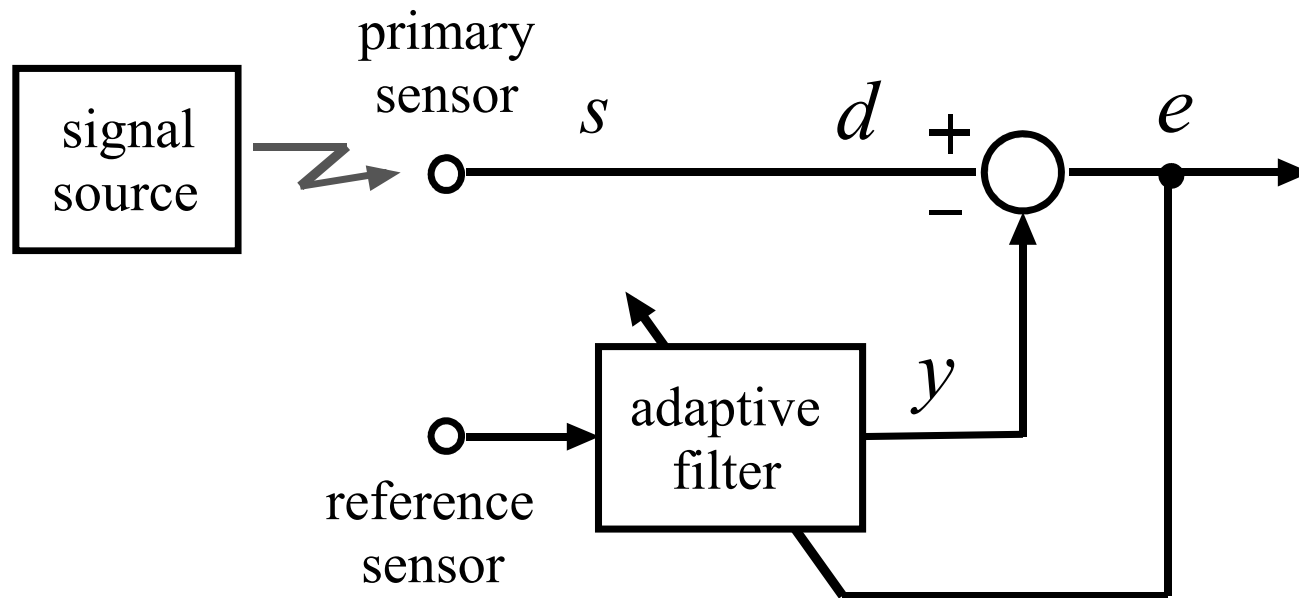
c) Equalization Application

- It is common to adjust filter at start of transmission using pre-arranged signal.



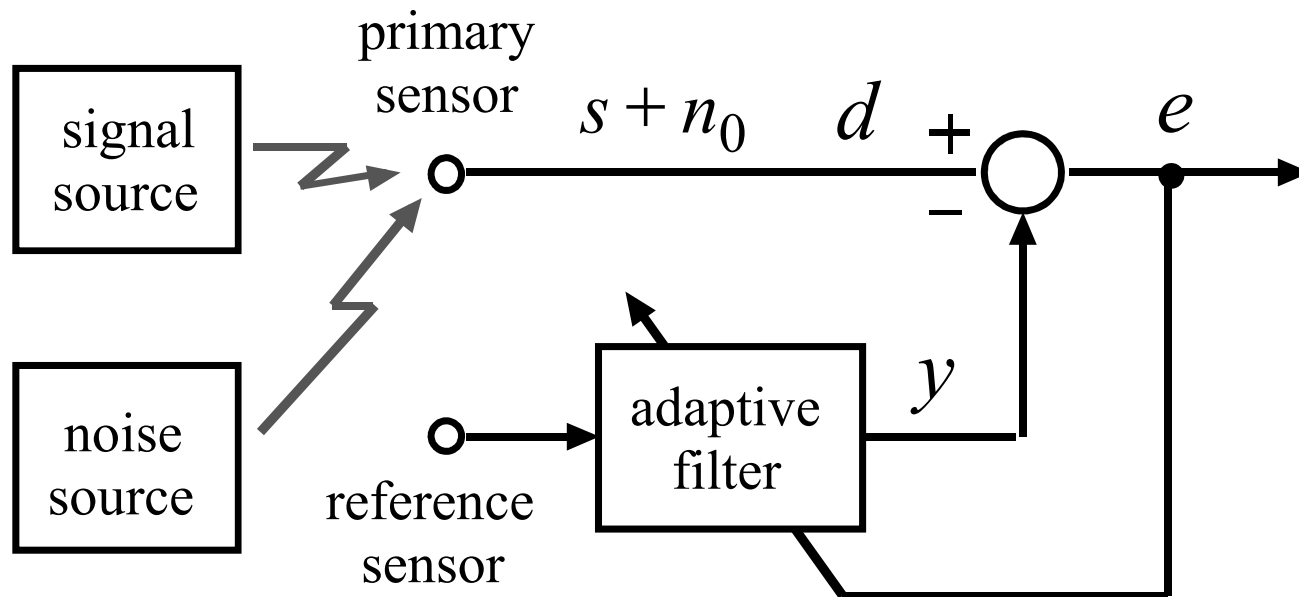
d) Noise Cancellation

- *primary sensor* picks up signal s



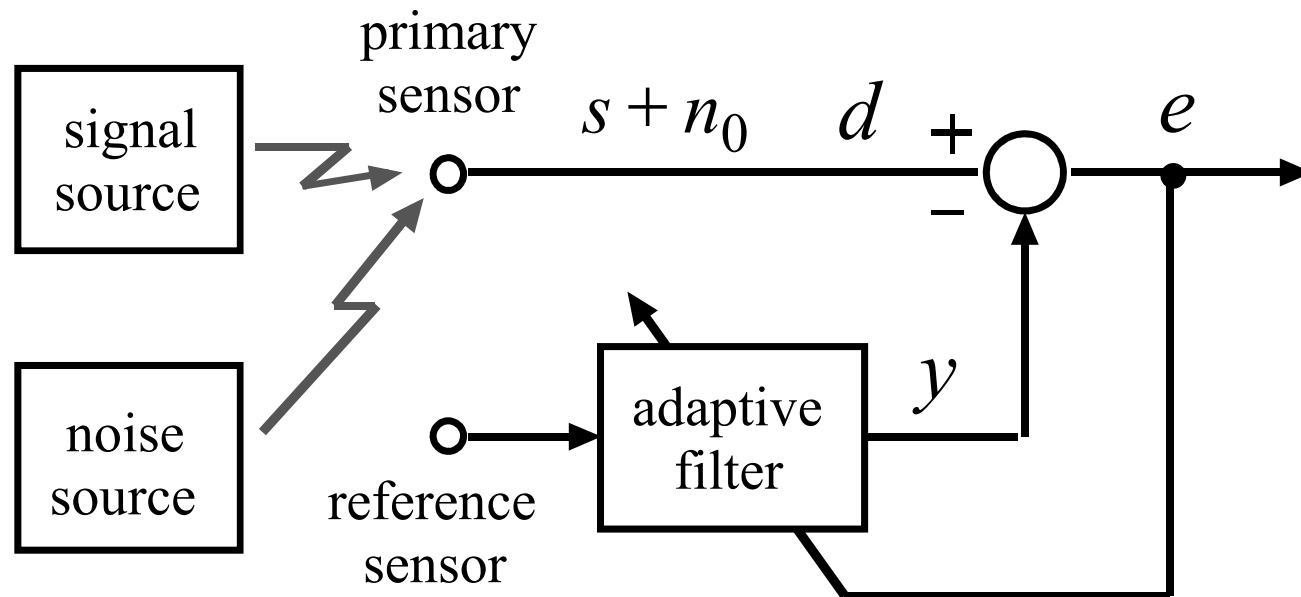
d) Noise Cancellation

- Unfortunately, this is corrupted by additive noise n_0 .



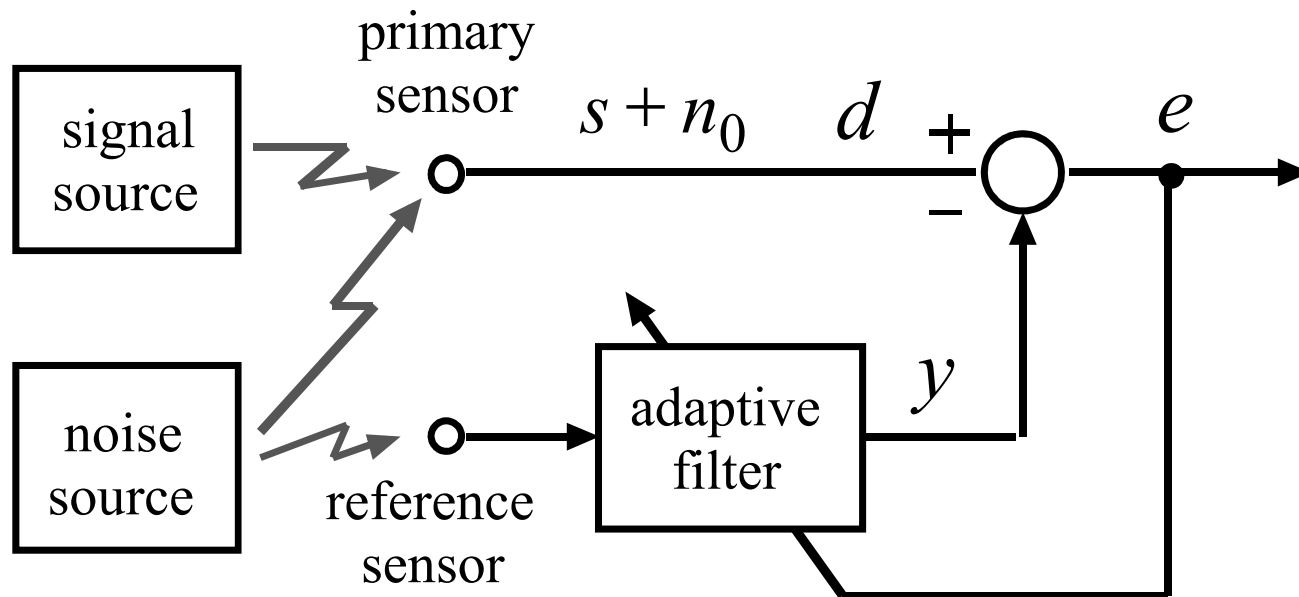
d) Noise Cancellation

- Noise canceller will attempt to subtract noise n_0 from signal at primary sensor.



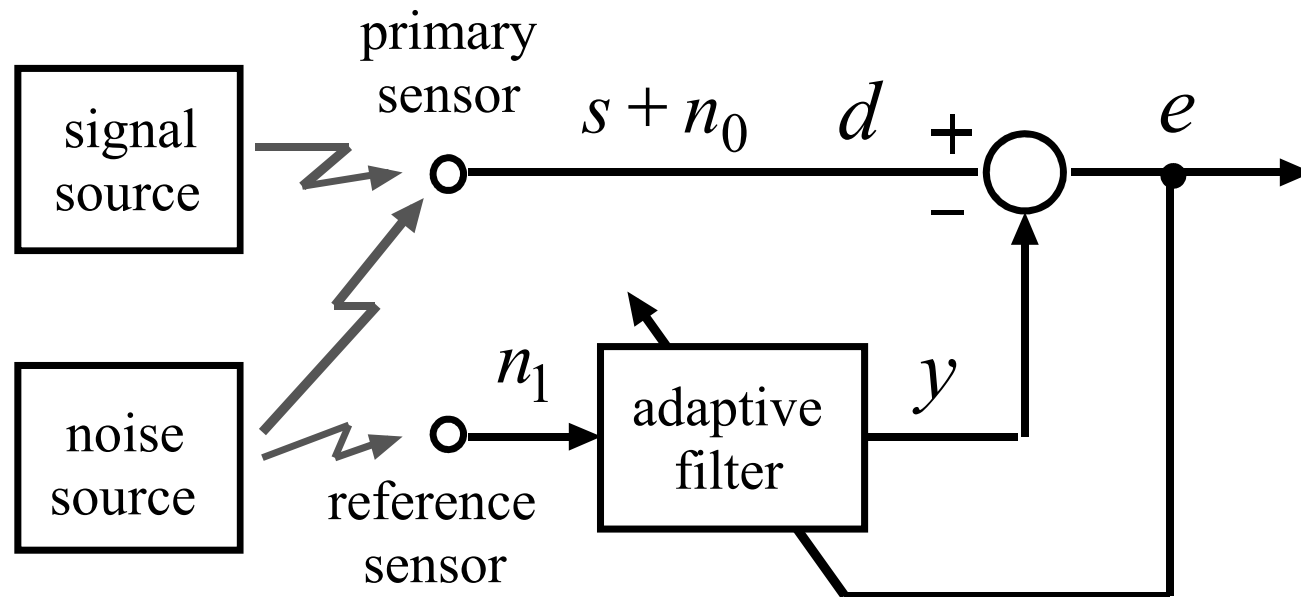
d) Noise Cancellation

- *reference sensor* positioned to pick up noise but not signal



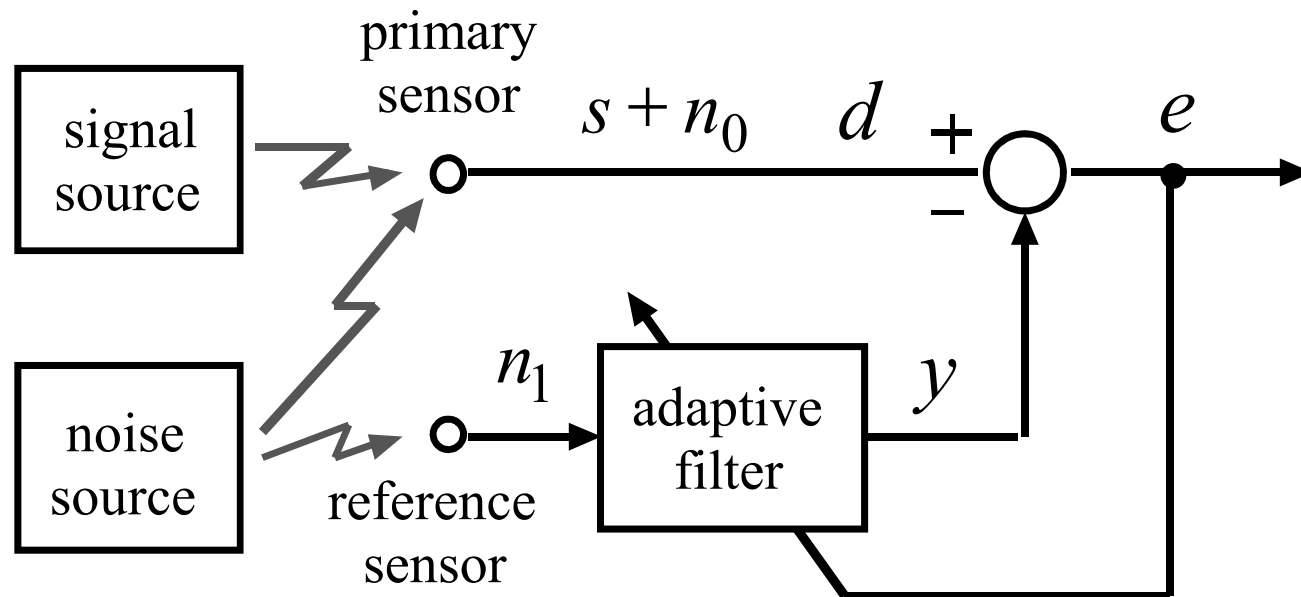
d) Noise Cancellation

- *reference sensor* positioned to pick up noise but not signal
- Reference noise n_1 is not identical to n_0 .



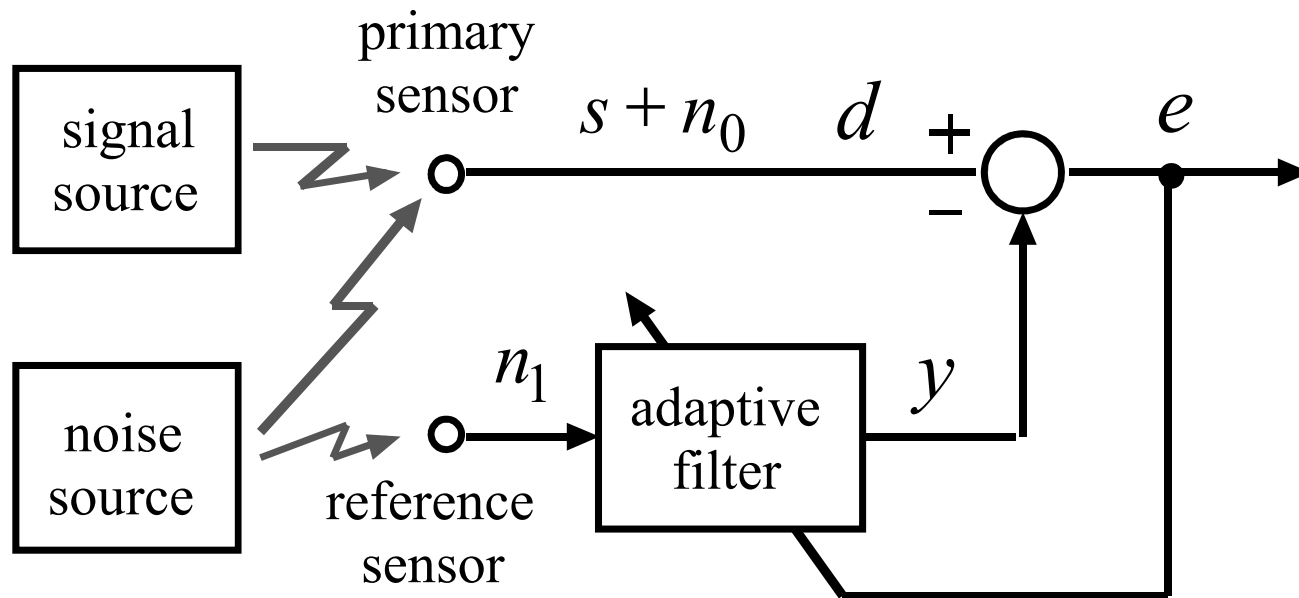
d) Noise Cancellation

- However, we will assume that n_0 and n_1 are correlated and each is uncorrelated with s .



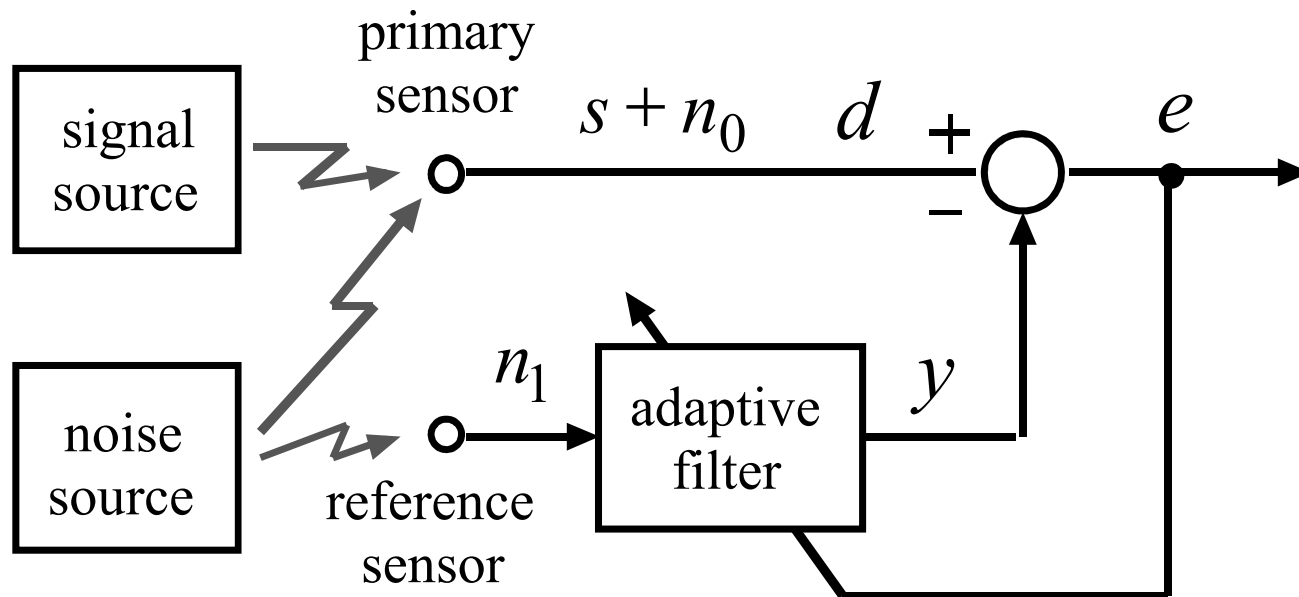
d) Noise Cancellation

- Role of adaptive filter is to estimate n_0 from n_1 .



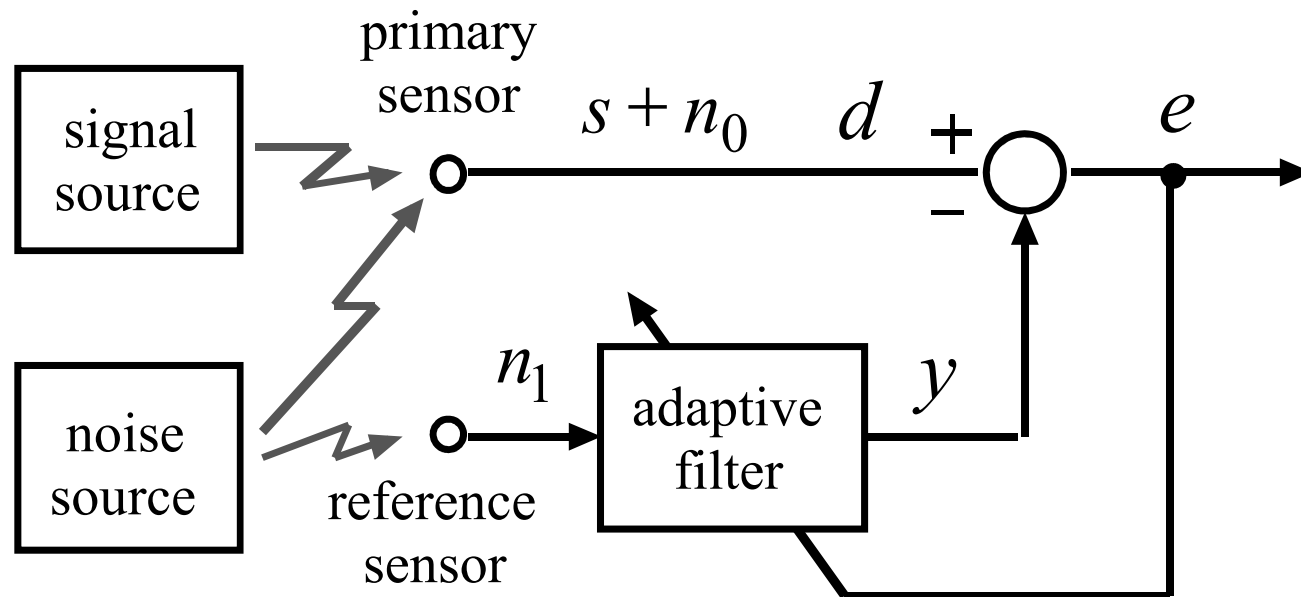
d) Noise Cancellation

- Role of adaptive filter is to estimate n_0 from n_1 .
- Intuitively, this appears feasible.



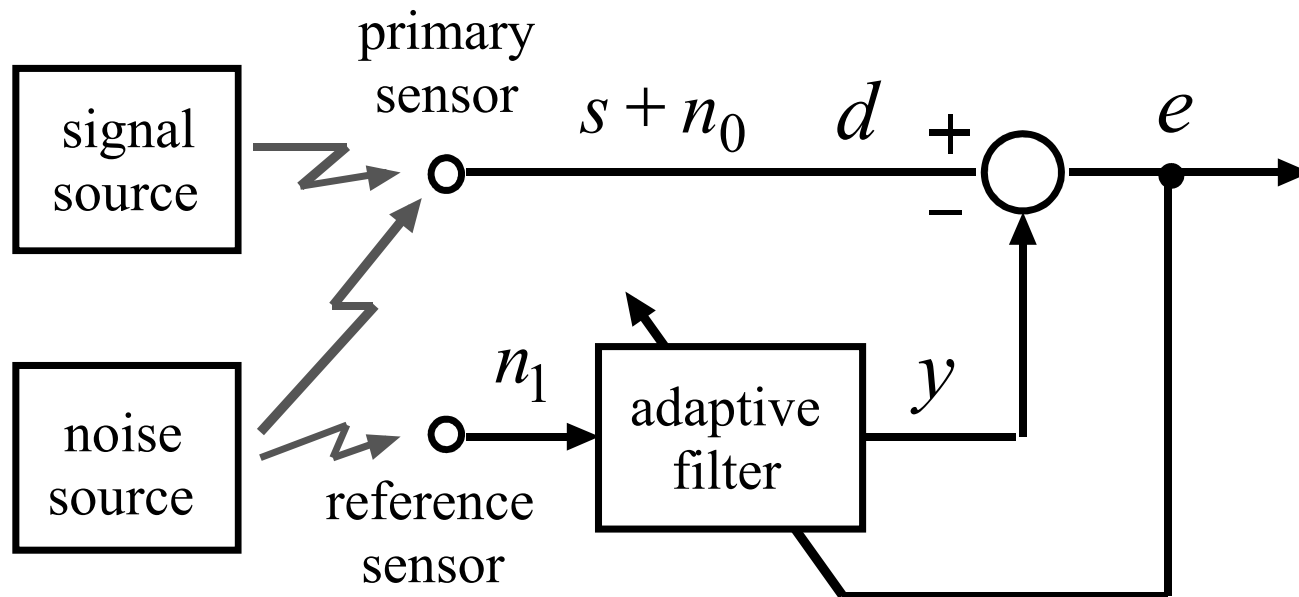
d) Noise Cancellation

- Adaptive filter seeks to minimize average power in signal e .



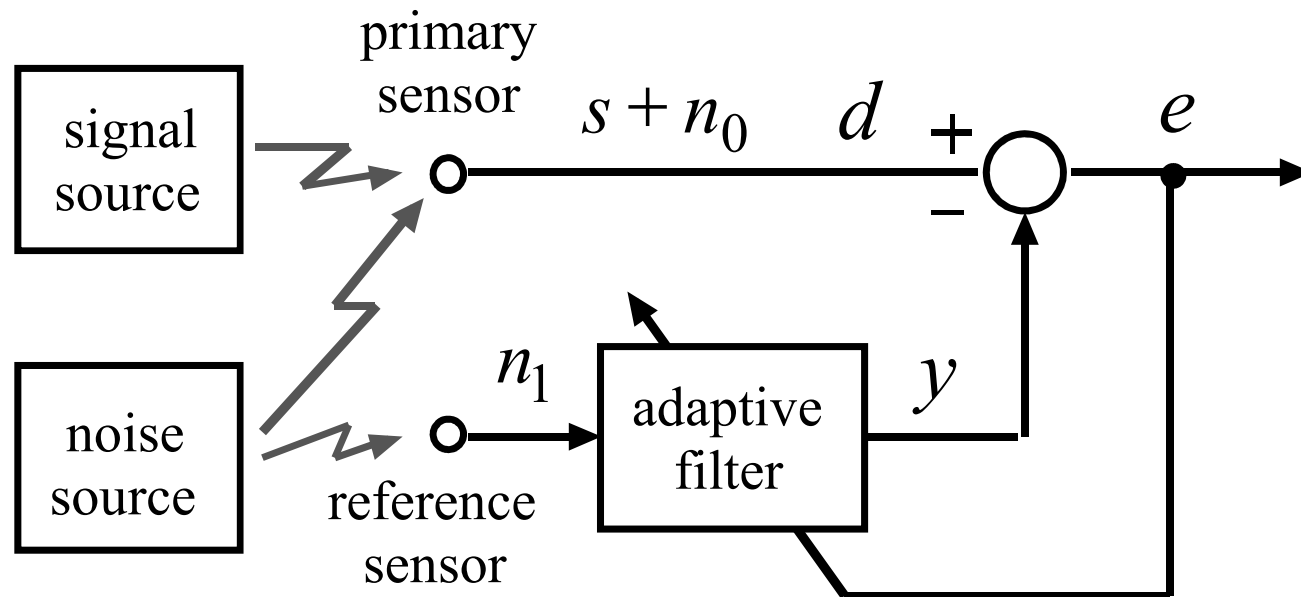
d) Noise Cancellation

- It is unreasonable to expect adaptive filter to estimate uncorrelated s from n_1 .



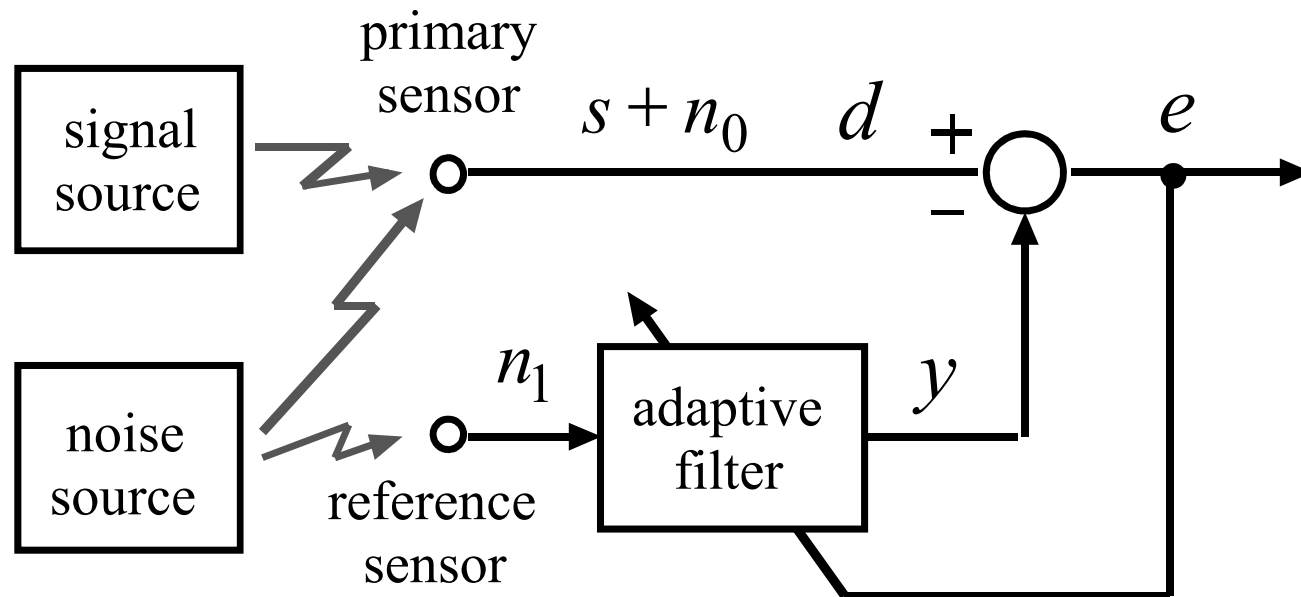
d) Noise Cancellation

- Minimizing average power in e equivalent to equaling average power in s



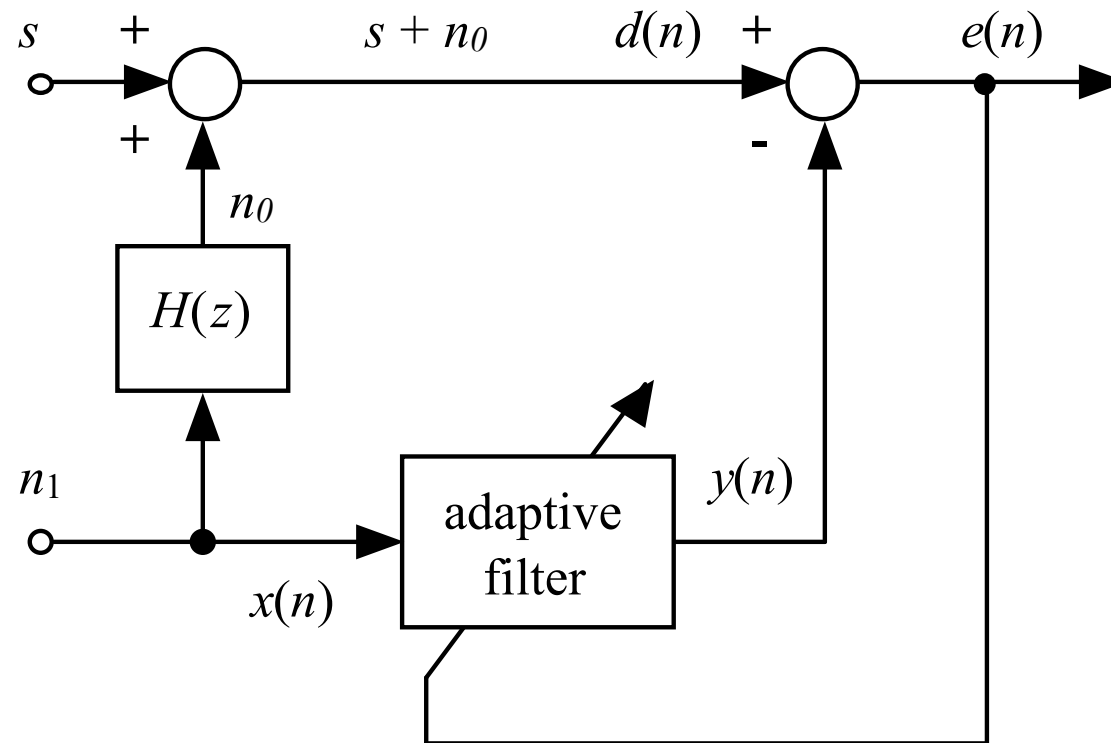
d) Noise Cancellation

- Effectively, adaptive filter learns difference in paths between noise source and sensors.



d) Noise Cancellation

- Noise cancellation application viewed as system identification problem



d) Noise Cancellation Applications

- aircraft cockpit noise
- electrocardiography

Closed Loop Adaptive Filter Configurations

- Four basic configurations are prediction, system identification, equalization, and noise cancellation.
- Common to each is the notion of adaptive filter minimizing average power in e .
- We can understand the applications without knowing exactly *how* adaptive filter works.